ABSTRACT

The following article describes a new flow deflecting fin system developed jointly in the GDR by the Institut für Mechanik of the Academy of Sciences of the GDR, Berlin, and the Schiffbau-Versuchsanstalt, Potsdam, during the past few years. It consists of simple fins of aerofoil cross section positioned forward of the propeller and is equally suitable for both new buildings and vessels that are already in service. Its main effect stems from a new way of imparting prerotation to the water entering the propeller on the side of the ship on which the propeller blades move upwards. Moreover, part of the energy dissipated in the wake field of the hull can be recovered and used for the propulsion of the ship by selecting appropriate fin arrangements and cross sections.

Experiments with the ship models investigated so far show that power savings of between 2 and 5% can be achieved. The basic saving of between 2 and 3½% resulting from the prerotation imparted to the water entering the propeller in independent hull shape.

The report describes the hydrodynamic considerations on which the development of the 3VA fin system in based. The results of tests with two models producing very different wake fields are briefly described.

NOMENCLATURE

\( C_T \) - Thrust loading coefficient of propeller \( C_T = \frac{T}{\rho V^2 A} \)
\( D \) - Diameter of a propeller (m)
\( F_D \) - Towing force in a self-rotation test (N)
\( j \) - Advance number of propeller \( j = V_A / n D \)
\( n \) - Rate of revolution (1/s)
\( \Delta n \) - Difference of rate of revolution (\%)
\( P_D \) - Delivered power at propeller \( P_D = 2 \pi n h (W) \)
\( \Delta P_D \) - Difference of delivered power at propeller (\%)

\( P/D \) - Pitch ratio of propeller
\( \tau \) - Torque (Nm)
\( \Delta \tau \) - Difference of torque (\%)
\( R_T \) - Total resistance (N)
\( t \) - Thrust deduction fraction \( t = (T - T_T + P_D)/T \)
\( T \) - Thrust (N)
\( \Delta T \) - Difference of thrust (\%)
\( V \) - Speed of ship (kn)
\( V_A \) - Speed of advance of propeller (m/s)
\( V_T \) - Circumferential component of velocity (m/s)
\( \eta_T \) - Taylor wake friction determined from thrust identity \( \eta_T = (V_V - V_A)/V \)
\( \Delta \) - Difference of self-propulsion test results with and without fins in general (\%)
\( \eta_H \) - Hull efficiency \( \eta_H = (1-\Delta)/\pi \)
\( \eta_R \) - Relative rotative efficiency
\( \rho \) - Mass density of water (kg/m³)

INTRODUCTION

Owing to the great increase in the proportion of the total running costs of a ship accounted for by fuel, the quest throughout the world for ways and means of improving propulsive efficiency, i.e., better utilizing the energy expended, has intensified in the course of the past two decades.

Besides the "classical" approaches to optimize energy consumption, such as

- improving hull shape to reduce ship resistance and raise propulsive efficiency,
- increasing propeller efficiency and
- improving the efficiency of engines,

during the past few years a variety of devices intended mainly to improve the flow of water to the propeller or to reduce the energy dissipated in the propeller jet have been developed, and in some cases applied in practice, to improve propulsive efficiency.

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As reported by R. Wagner in his excellent review and Prospects of Counter-propeller Development in volume 30 of the annual of the Schiffbautechnische Gesellschaft in 1929, the principles upon which flow-deflecting devices to interact with the propeller were known to naval architects and exploited over 70 years ago. Nevertheless, in the last decades devices of this kind have been developed, patented and used in various shipbuilding countries, ranging from asymmetric sterns (Wöllming, Federal Republic of Germany), guide vanes (propeller jet unit) and fin rudders (Mitsubishi, Japan) to guide vanes on the rudder (Kawasaki, Japan), to mention only a few.

Practical solutions were also sought in the GDR. The fin system described in this report was developed jointly by the Institut für Schiffbautechnik (IFSS) and the Schiffbau-Ver suchsanstalt (SVF) in Potsdam and has been thoroughly tested in model experiments. In principle it is suitable for use on all single and multiple screw ships and can also be propelled to vessels that are already in service.

CONSIDERATIONS

The numerous sources of losses in the flow around a ship and in the propulsion arrangements can be divided into two broad categories. The first consists of the losses that arise owing to the principles involved and must be minimized by finding the optimal combination for each specific design. They include, for instance, the energy of the axial component of the propeller jet and frictional losses on the hull, propeller and rudder. The second category consists of losses that can all theoretically be avoided, but, such as flow separation on the after-body, the generation of large, energy consuming eddies, and the kinetic energy of the larger components of the propeller jet, the so-called spin losses.

Spin losses can only be eliminated or reduced by "unnatural" means because they are a consequence of energy transfer by rotating parts of a turbine and therefore have a unique relation and eddy generation are a result of hull shape and can be reduced or even avoided by the appendages of the reaction surfaces. Multi-bladed propellers, with the upper part of the propeller digging into the water and Grothusen's spoolers to deflect the vertical component of the flow in the boundary layer close to the hull forward of the propeller are well known and typical examples of such devices.

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of the propeller is that they can be used additionally to deflect the flow near the wall of the vertical component of the boundary layer are reversed and therefore the energy in these components can then also be utilized.

To make fullest use of the potential offered by the reaction fins it is also necessary to modify the propeller to the modified flow pattern. This can lead to an additional 2% saving in energy by improving propeller efficiency.

DESCRIPTION OF FLOW AT THE STEM AND SELECTION OF FIN SYSTEMS FOR TWO ACTUAL SHIPS

Since the flow of water to the propeller depends on hull A, the flow from ship to ship, ships with a fine block coefficient often have an upward-directed flow over the whole radius of the propeller discs at the propeller centre level like hull A in Fig. 7, whereas the vertical components of the flow are often reverse their direction near the hull of ships with a fuller block coefficient, such as hull B, owing to large eddies in the wake field on either side of the propeller shaft. These energy-dissipating eddies are caused by the shape of the frames of the fore and middle-bodies, and they can usually only be slightly influenced by structural arrangements further aft, including asymmetric stern designs. The provision of reaction fins on the hull to generate the necessary propeller forward of the propeller is also an alternative way to avoid at least part of the energy dissipation in such secondary eddies caused by hull B.

The fin system developed by GVA consists of simple components of aerofoil cross section attached to the hull-forward of the propeller. The actual configuration depends on the flow pattern caused by the hull in the water entering the propeller disc, consisting in general of a horizontal and, if necessary, a vertical fin filled to one side of the hull level with the propeller shaft. In the simplest case, such as hull A, the fin system consists of only a single horizontal fin on one side of the vertical on which the propeller blade move upwards. The purpose of this arrangement is to deflect the upward, energetically "incorrectly rotating" flow downwards. On the other side, the flow already takes the energetically desirable direction of its own accord.

For hull B the fin system consists of a horizontal fin on the "upward" propeller side, which deflects the, flow downwards over the whole radius of the propeller, and a much shorter fin on the other side to deflect the "incorrectly rotating" component of the flow in the boundary layer close to the wall.

It is naturally best to use as few fins as possible since the optimization of the system and the construction of the full scale structural components becomes increasingly complex as the number of fins increases.

MODEL EXPERIMENTS

The effects of the new fin system were tested mainly by self-propulsion experiments. The main criterion used for optimization was minimization of the power need for propulsion, attention simultaneously being given to possible side effects affecting vibration characteristics. Since the aim of the self-propulsion experiments was to detect differences in the region of one per cent, particularly it was for every test series, for instance, the tests with and without fins were performed on the same day to eliminate right from the start all experiment errors that might be caused by differences in test conditions.

The results of the self-propulsion tests with optimal fin configuration for hulls A and B are presented in Fig. 4 and 5. The benefits are expressed as percentage reduction in thrust and propeller speed, and in the propulsion power calculated from torque and propeller speed, obtained through the effects of the fin system relative to the same hull without fins.

As can be seen from Fig. 4, the power saving was over 2,5% for hull A and varies almost in proportion to the speed. It stems mainly from a reduction of at least 2% in propeller speed. The fact that the remaining unchanged permits us to conclude that the fins produce a thrust that is at least equal to the additional resistance they cause.

Fig. 5 shows that for hull B the reduction in propulsion power ranges between 4 and 5% and is almost constant for the speed range investigated. This power saving results from a reduction of almost 3% in the necessary propeller speed, largely due to the generation of prerotation forward of the propeller disc, and of roughly 2% in the torque requirement and even in the case of hull B, less energy was dissipated in the whole of the flow to the propeller owing to at least partial suppression of eddy generation as described in Chapter 3.

The thrust deduction fractions, which fractions and relatively efficiencies, with which the naval architect and constructor, are shown without correction as calculated from the propulsion tests in Fig. 6 and 7. The thrust deduction fractions were calculated for the models with and without fins using the resistance without fins or other appendages. The thrust fractions were uncertain in the customary way for identical thrusts.

It is evident from Fig. 6 that the thrust deduction fraction, t, remains approximately the same for hull A because the thrust does not change, whereas the mean coefficient, Mr, increases as a result of the reduction in propeller speed permitted by the fin system. The hull efficiency, Cp, is therefore correspondingly higher. There is close agreement between the values of Cp for the hull with and without fins in consequence of the term mentioned earlier with which the experiments were performed.

Fig. 7 shows that for hull B the influence of the fin system on the parameters characteristic for the relative hull efficiency are greater owing to the greater
effect of the fins. The thrust deduction fraction, \( t \), is smaller as a result of the lower thrust required, and the wake coefficient, \( W_t \), is larger due to the lower propeller speed. The values of \( W_t \) for the model with fins are considerably higher than for that without them, but, as in the case of hull A, the values of \( W_t \) are almost identical for both versions.

CONCLUSIONS

It has been shown that the new SVA flow deflecting fin system we have described, and which has been the subject of numerous tank tests, can yield power savings of between 2 and 3% for several single-screw ships with low thrust:load coefficients, and that these savings will be even larger on the actual ships concerned owing to the higher Reynolds numbers. The basic gain of 2 to 3% resulting from the generation of prerotation in the water flow to the propeller can theoretically be obtained with the new fin system for all ships if the propeller load is high enough. This basic gain represents a saving that is independent of hull shape.

The fin system is not only suitable for newbuildings, but can also be retrofitted to vessels already in service. In the latter case, however, it is necessary to check whether the propeller and propulsion arrangements permit the corresponding reduction of pitch. Where newbuildings are concerned, of course, the propeller must naturally be adapted to the propulsion arrangement with reaction fins. This will yield an additional saving in power.

Apart from its principal effect, the reduction of power requirements, the fin system, owing to the asymmetric fin arrangement, also results in more uniform loading, thus probably reducing vibration induced by pressure pulses, thrust eccentricity, and susceptibility to cavitation.

![Energy Balance for a Wageningen B 4.55 Propeller with a Pitch Ratio of 1.0 in Open Water](image)

\[ J = \frac{V_A}{n \cdot D} \]
Fig. 2. Spin Loss of Wageningen B 4.55 Propeller as a Function of Thrust Load Coefficient, $C_{Th}$, and Pitch Ratio, P/D
Shaded area: Working Range for Normal Single-Screw Vessel

$C_{Th} = \frac{T}{\frac{D^2}{4} \frac{\pi}{2} \frac{V^2}{4}}$

Fig. 3. Tangential Velocity Components in the Propeller Disc Plane

$\nu_s \over \nu = 0.2$

Hull A

Hull B
Fig. 4. Hull A, Influence of Fins on Measured Propulsion Values

Fig. 5. Hull B, Influence of Fins on Measured Propulsion Values

Fig. 6. Hull A, Propulsion Parameters

Fig. 7. Hull B, Propulsion Parameters